

# Forensic Applications in 3D Imaging

The case for Foundational  
Validation



THE UNIVERSITY  
*of* ADELAIDE

We acknowledge and pay our respects to the Kaurna people,  
the traditional custodians whose ancestral lands we gather on.

We acknowledge the deep feelings of attachment and relationship of the  
Kaurna people to country and we respect and value their past, present  
and ongoing connection to the land and cultural beliefs.

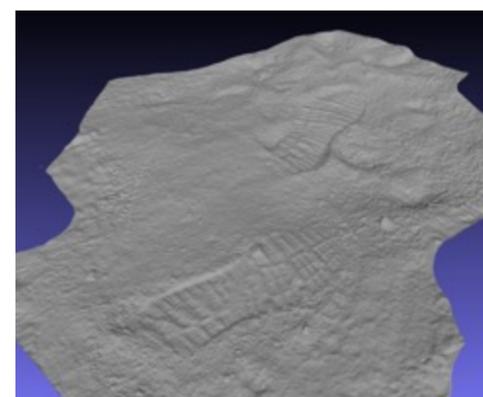
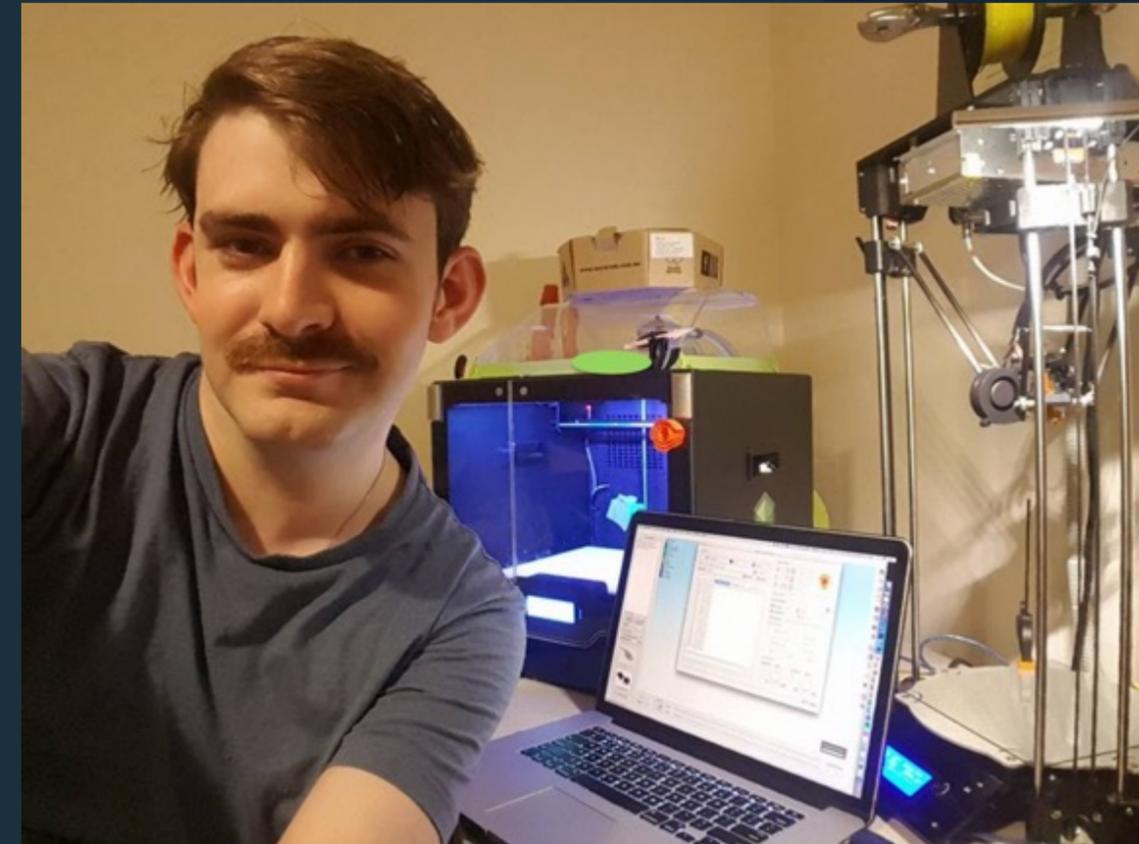
# Biography

I'm an engineer and forensic scientist in Adelaide, South Australia who has been printing and designing models ever since my boss at GM Holden dropped a 3D Printer on my desk as part of a community outreach program with local schools.

I've played with dozens of printers ranging from hobby to commercial grade and designed numerous engineering models and parts for business, schools and consumers alike. I began scanning models in 2018 when I started writing courses in 3D printing and prototyping for the University of Adelaide.

In 2019 I was awarded my PhD in digital forensic science. Since then, I have been exploring interdisciplinary topics such as the applications of machine learning, open-source intelligence and various mental models that can be applied to our domain of forensic science.

I've regularly appeared in the media on topics relating to 3D printed firearms and other applications of this technology for our profession.



# Today

- **Applications of 3D Imaging**
- **The Case for Foundational Validity**
- **A Pipeline Model for 3D Imaging**
- **Assessing Error in the 3D Pipeline**

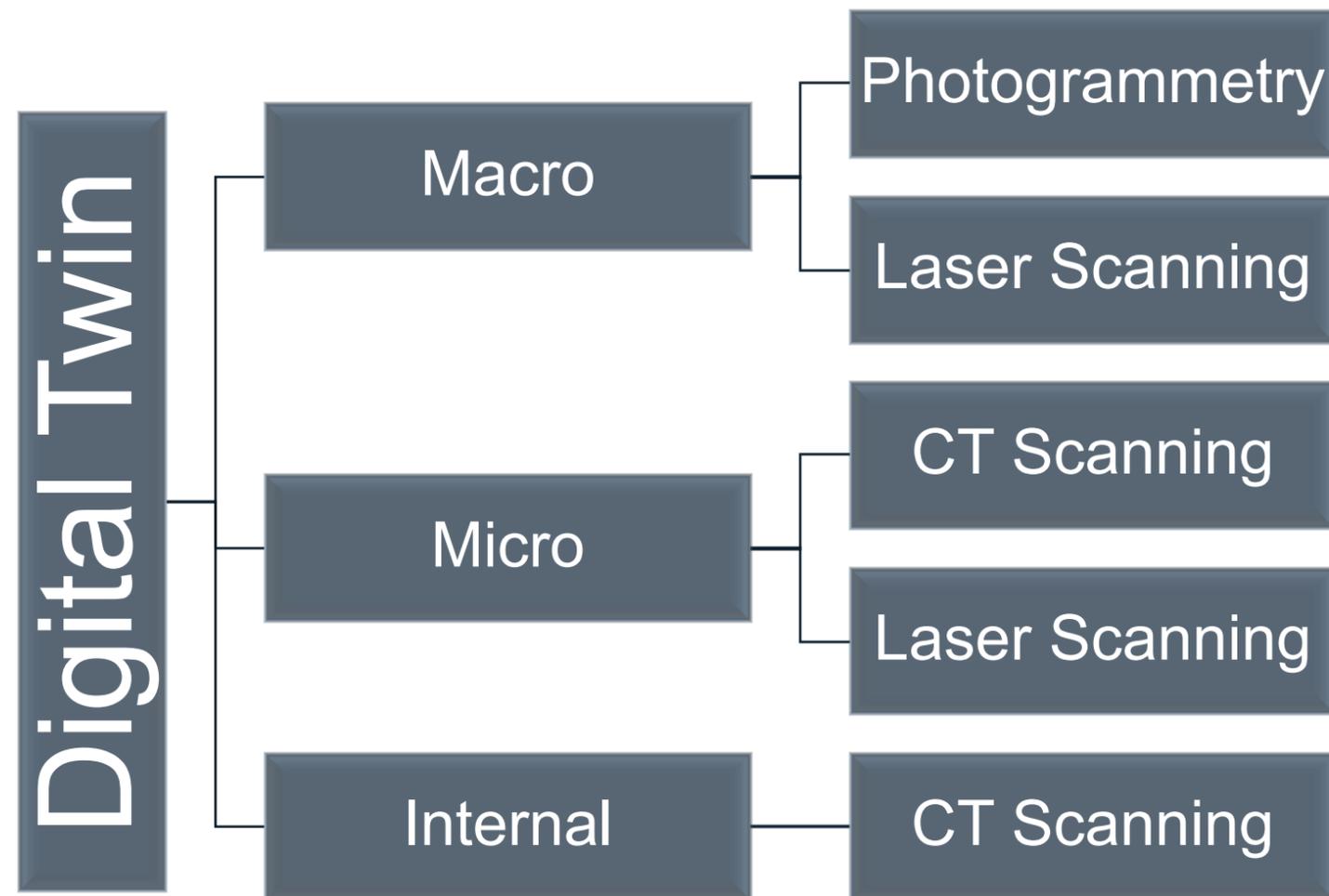


# Conception

## Digital Twin

“A virtual representation that serves as the real-time digital counterpart of a physical object or process.”

(Attributed to Michael Grieves, 2002 then University of Michigan)



Elisa Negri (2017). "A review of the roles of Digital Twin in CPS-based production systems". *Procedia Manufacturing*. **11**: 939–948.

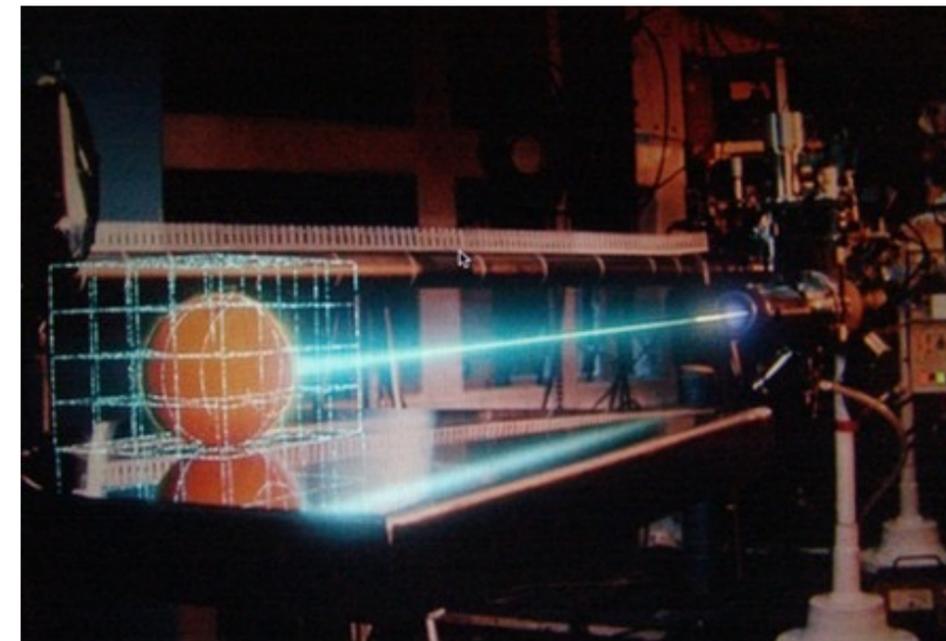
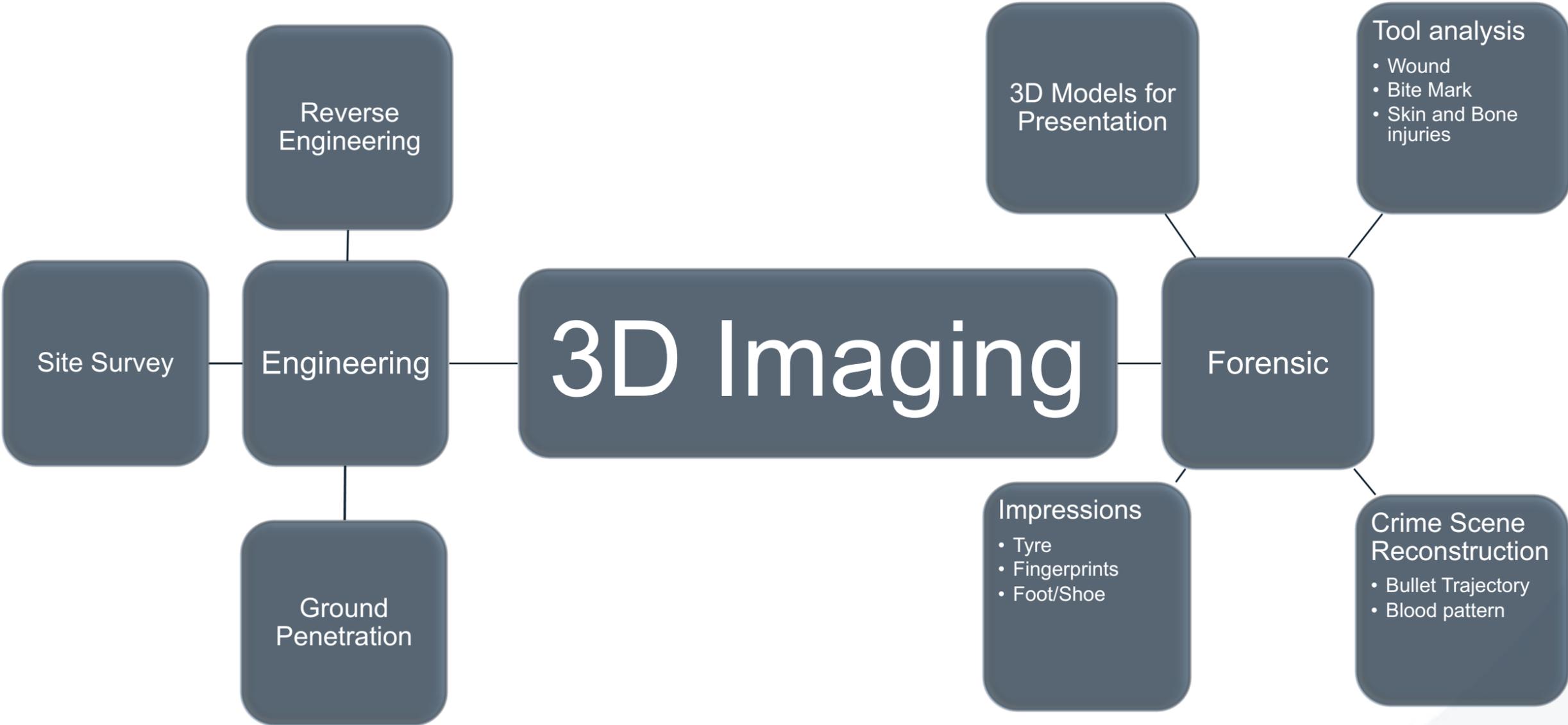


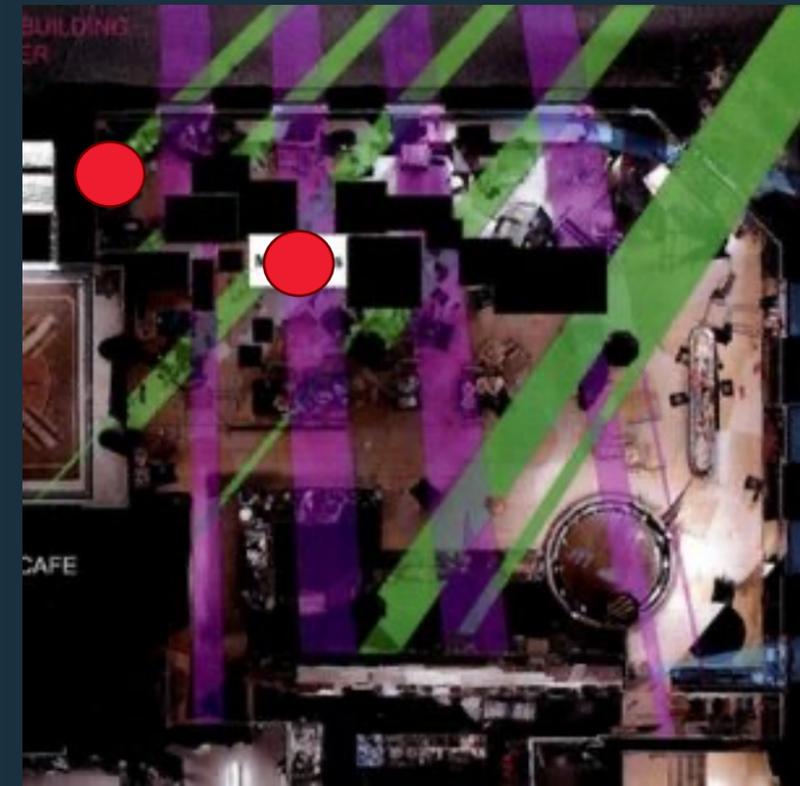
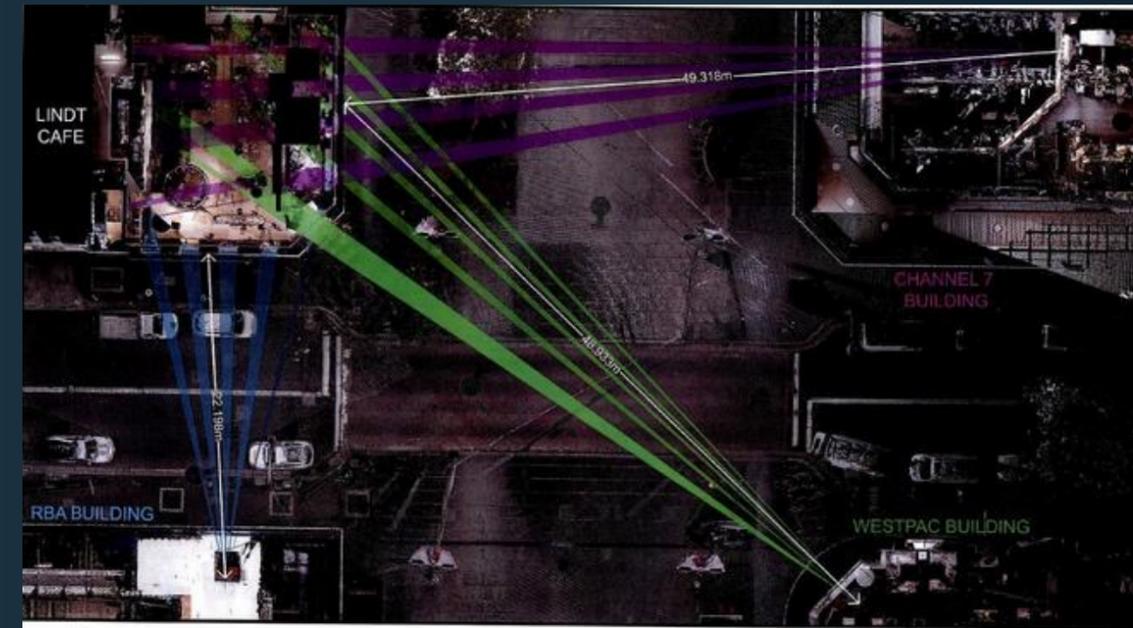
Image Credit:  
Tron. (1982). Lisberger, S. Walt Disney Productions

# Application Space

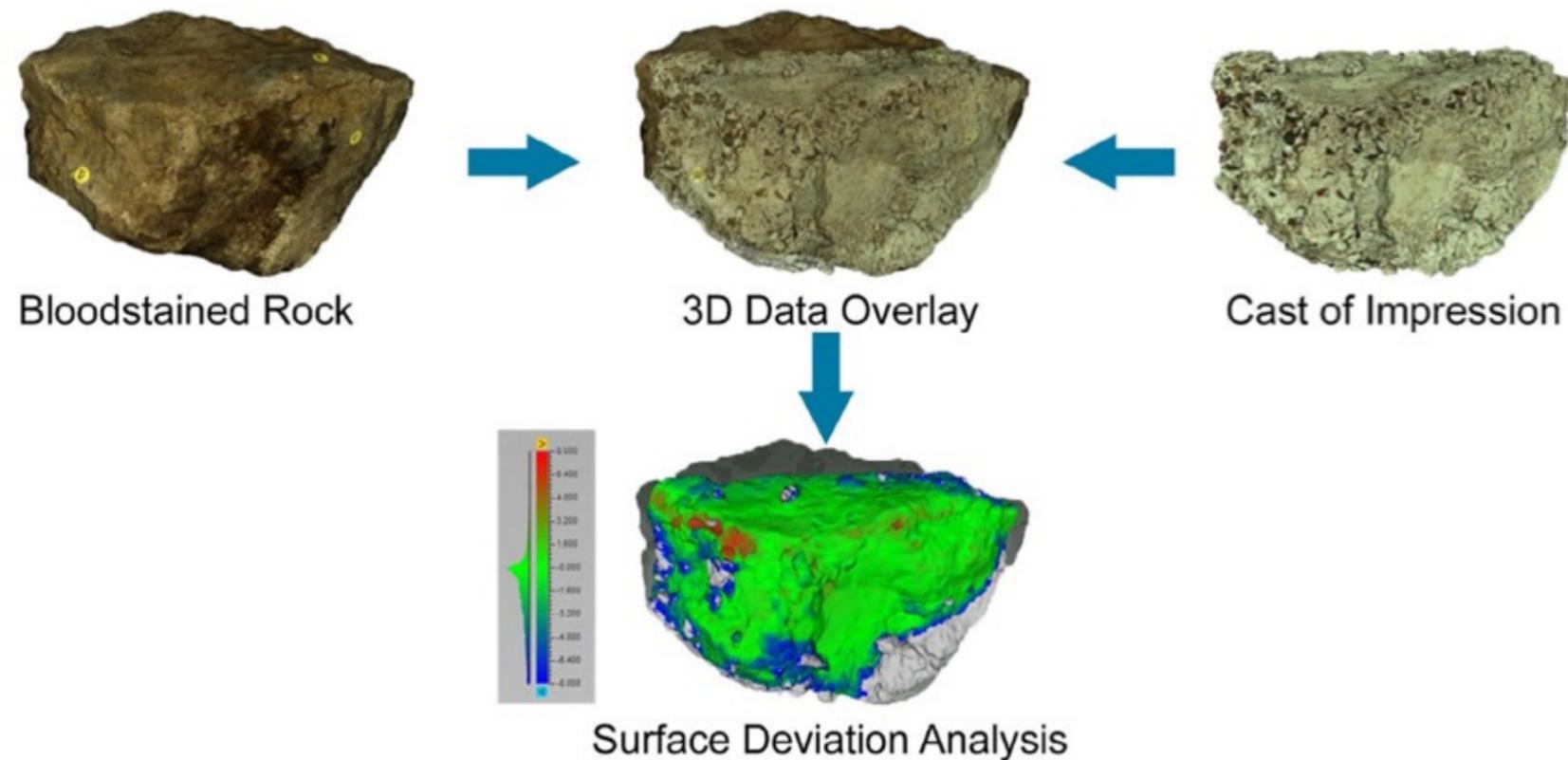


# Crime Scene Reconstruction: Lindt Café Siege

- Tripod mounted 360° scans supplemented by exhibit scans
- Review trajectories and likely positions using field of view analysis, CCTV, and audio analysis.
- 3D fly throughs created of the scene.
- Conclusions drawn regarding EA and the unintentional killing of Katrina Dawson.



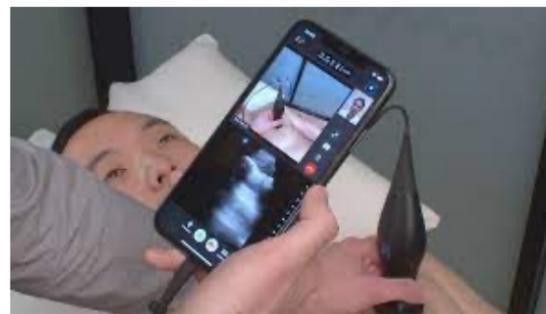
# Tool and Impression Analysis: Homicide



- Rock used to bludgeon victim to death.
- Weight of exhibit caused issues with examination
- Matching to impression

# Synthesis

Ubiquitous scanning on demand?



What does forensic science and Star Trek: Picard have in common?



# Previous work

- 2019 Honours projects at the University of Adelaide funded by the Australia and New Zealand Policing Advisory Agency National Institute of Forensic Science.
  - Tang, J. 2019. Forensic Applications of 3D Scanning. Honours. University of Adelaide. Adelaide South Australia.
  - Walsh, G. 2019. Forensic Applications of 3D Scanning. Honours. University of Adelaide. Adelaide South Australia.

**Could we create low cost a ubiquitous scanner?**

**What does forensic science and Star Trek: Picard have in common?**

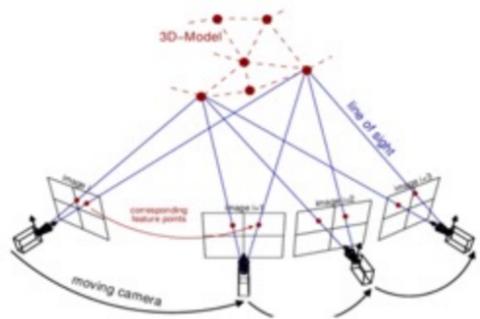


# Our aims

- **Compare a selection of 3D imaging technologies**
  - Photogrammetry
  - Laser Scanning
  - Dot Projection
- **View in the context of two key application spaces**
  - Blood Pattern Analysis
  - Shoe impressions



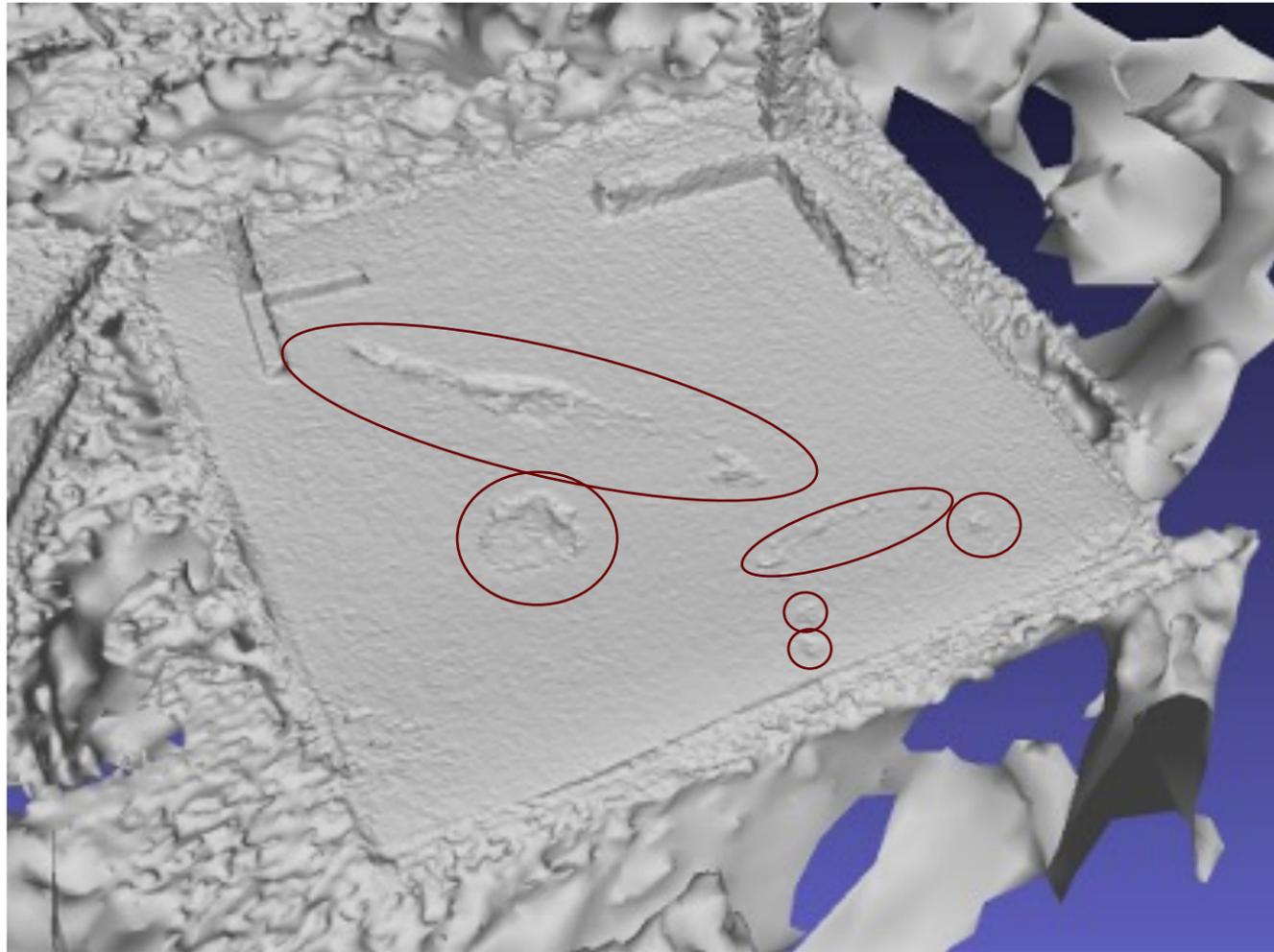
# Experiment



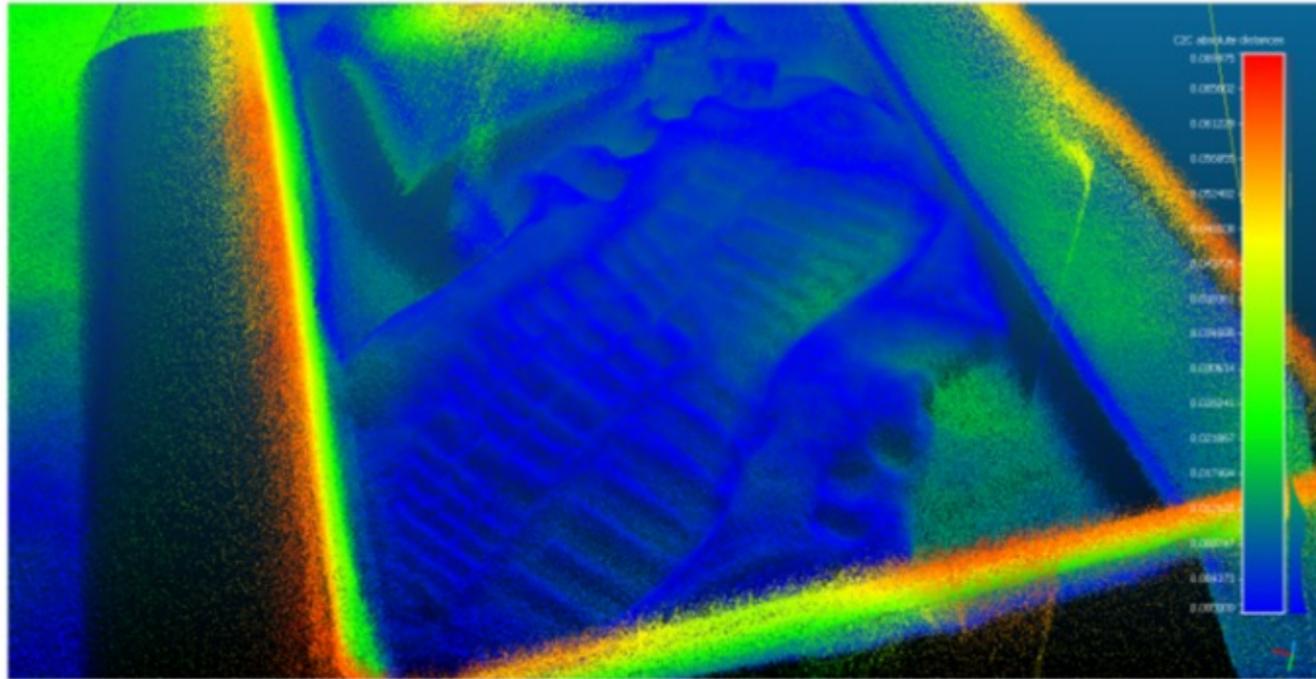
<b>J</b>	Superfine Self-raising Flour (Waitrose)	39g	Mix to a homogeneous constituency and store at room temperature
	Sodium Chloride (Sigma)	1g	
	Glycerol (Supercook)	1ml	
	Strawberry Sugar Syrup (Lyles)	1ml	
	Scarlet Food Colouring (Supercook)	1ml	
	Sterile Distilled Water	183ml	

Goldilocks Principle

# Blood Pattern Analysis



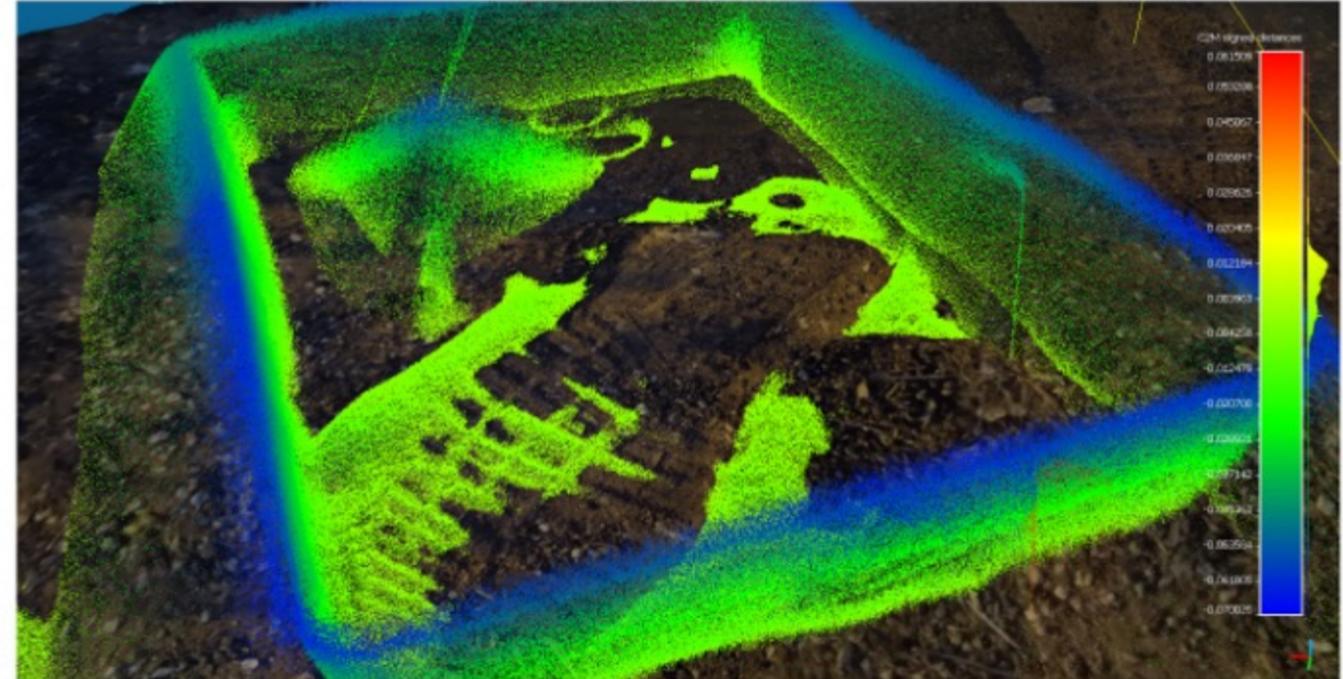
# Footwear: Surface Deviation Analysis



Photogrammetry to Laser scan point cloud comparison. Value in absolute distance.

(Scale: blue = 0 red =0.07 m)

0 difference across the impression



Laser Scan point cloud to Generated Mesh comparison

(Scale: blue = -0.07 red =0.06 m)

- 4mm is difference across the print

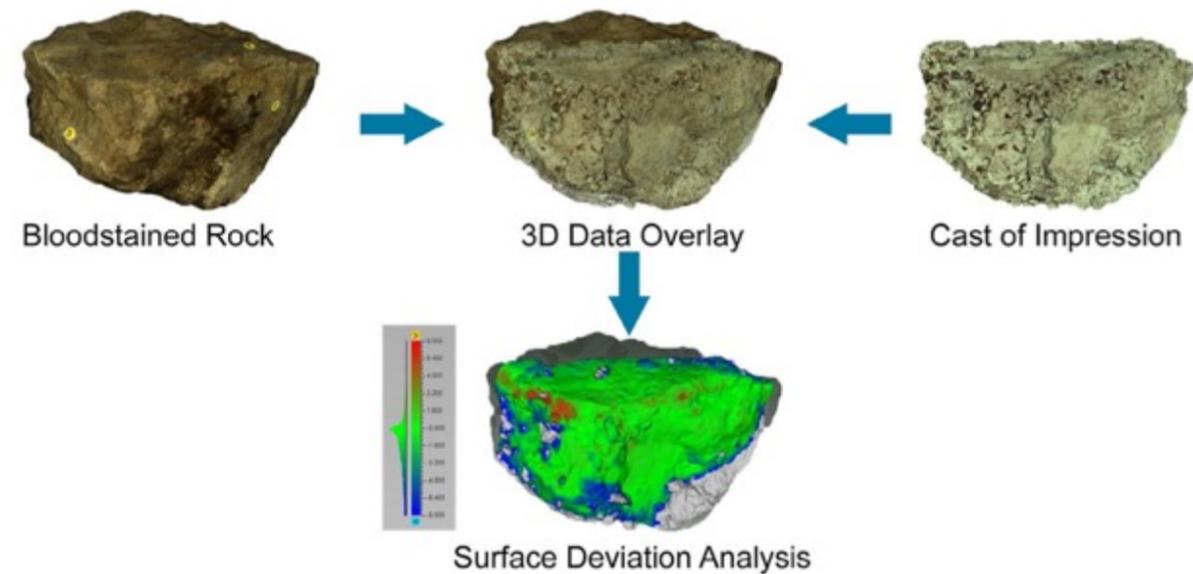
# Results

- Photogrammetry is an acceptable low-cost method of 3D imaging for most applications
- There are issues with precision loss when converting from point cloud to mesh.
- Blood and other specular applications resist scanning
- Precision of survey equipment may not be sufficient to create digital twin of blood pattern evidence – no gain over simple images bar digital workflow improvements.
- Use the right tool for the job.

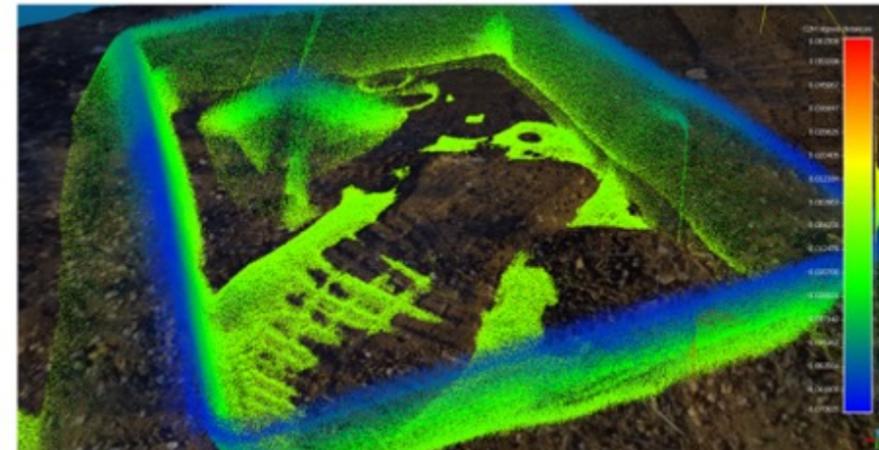
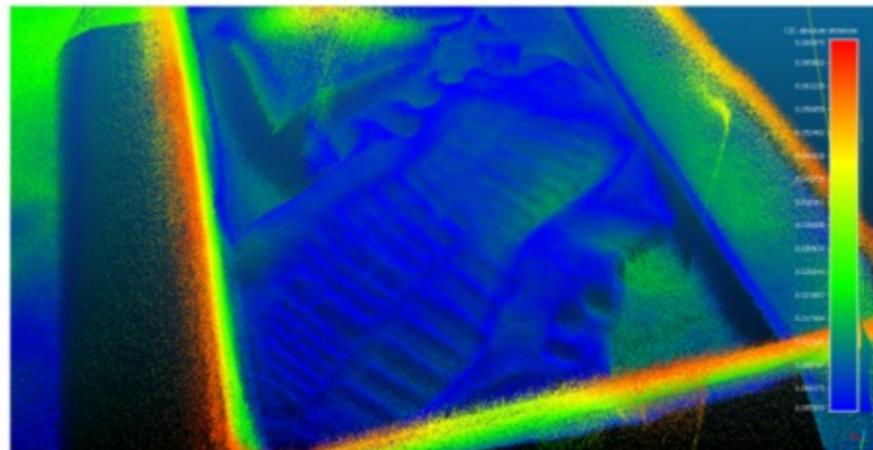


# Limitations

## Foundational Validity?



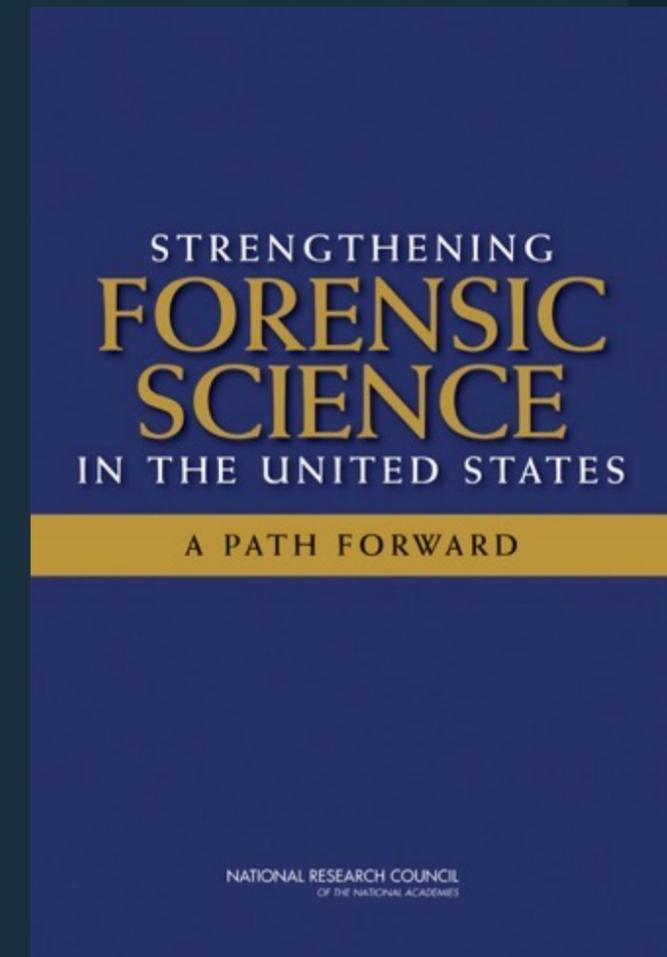
- Where are the losses in the system?
- How do we quantify them?
- Are these errors acceptable?
- Do we understand them?
- What are the standard processes?



# Foundational Validity

*“The interpretation of forensic evidence is not always based on scientific studies to determine its validity.”*

- National Research Council of The National Academies



2009

2016

2020

2021

2023

# Foundational Validity

- Expanded upon the findings of NAS in critical areas:
  - Footwear, Firearms, DNA, Bite Marks, Fingerprints, Hair Analysis.
- No studies can answer if a cast came from a particular piece of footwear
- I.e. we cannot say if a particular impression came from a specific shoe based on identified marks



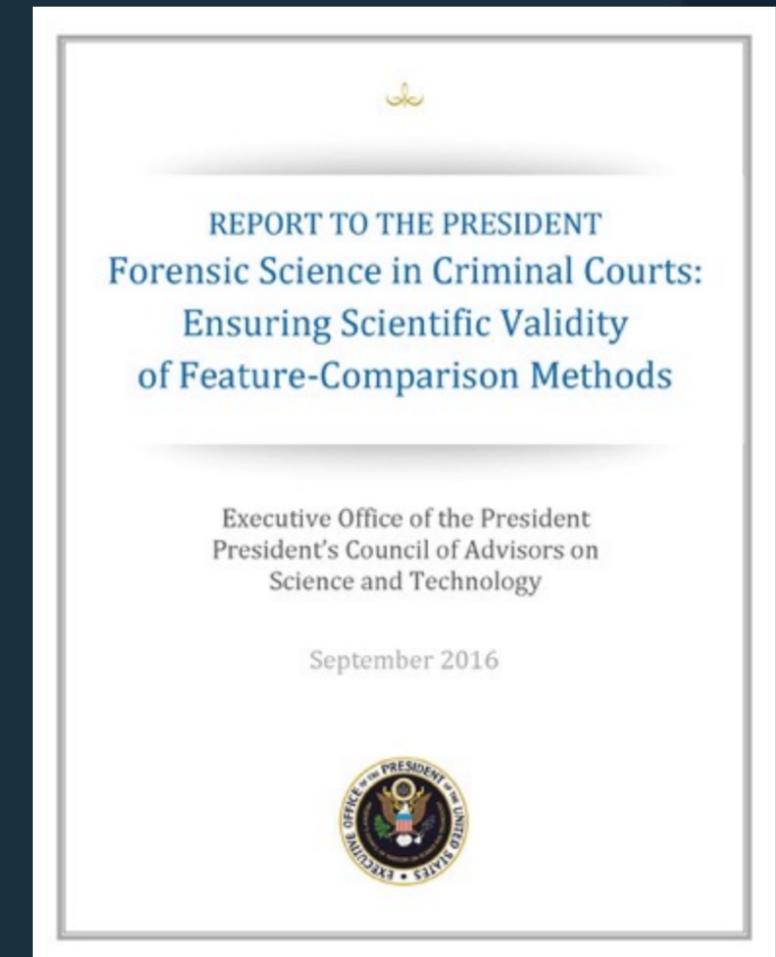
2009

2016

2020

2021

2023



# Foundational Validity

- Rejected the findings of PCAST and not the only ones who have done so.
- Rejection based several critical points.
- The method of validation used in PCAST is not the only possible method of validation.
- Forensic Science does not meet the definition of measurement.



2009

2016

2020

2021

2023

# Foundational Validity

## Forensic Science Definition

Forensic science is a case-based (or multi case-based) research-oriented endeavour using the principles of science to study and understand traces – the remnants of past activities (such as an individual's presence and actions) – through their detection, recognition, examination and interpretation to understand anomalous events of public interest (e.g., crimes, litigations, security incidents).

1. Activity and presence produce traces that are fundamental vectors of information
2. Scene investigation is a scientific and diagnostic endeavour requiring scientific expertise
3. Forensic science is case-based and reliant on scientific knowledge, investigative methodology and logical reasoning
4. Forensic science is an assessment of findings in context due to time asymmetry.
5. **Forensic science deals with a continuum of uncertainties.**
6. Forensic science has multi-dimensional purposes and contributions
7. Forensic Science findings acquire meaning in context

<https://iafs2023.com.au/cms/wp-content/uploads/IAFS-2023-Sydney-Declaration-18-May-2021.pdf>

**Sydney Declaration**  
18 May 2021



2009

2016

2020

2021

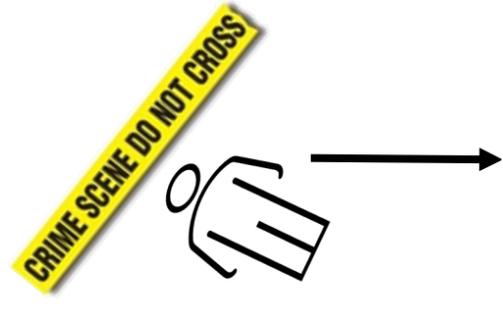
2023

# Addressing this issue for 3D imaging

- **Introducing a new concept for visualising the 3D imaging process using a systems engineering method of decomposition and reduction.**
- Basic steps taking evidence from scene to court room
- Consideration for additive/subtractive manufacturing technology
- Identification of likely sources of error
- Clustering of steps into easily identified stages or sub-systems.



# Traditional Process



*Crime Scene*



*Source of Bias  
(A)*

*Expert report and  
object for Jury*



*Court Room*



*Source of Bias  
(G)*



*Expert Witness*

*Source of Bias  
(F)*

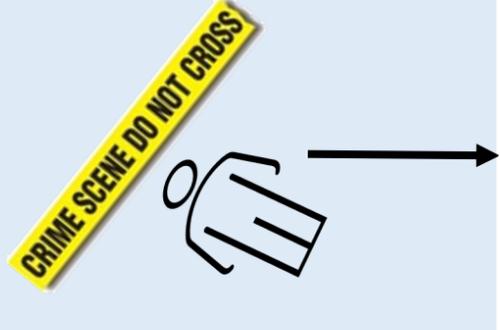


# Traditional Process



For notation simplicity all errors are assumed to be read as Root Mean Squared except where obviously not meant to be.

# Traditional Process



Crime Scene



Source of Bias (A)



Long term Data Storage

Expert report and object for Jury



Court Room



Source of Bias (G)

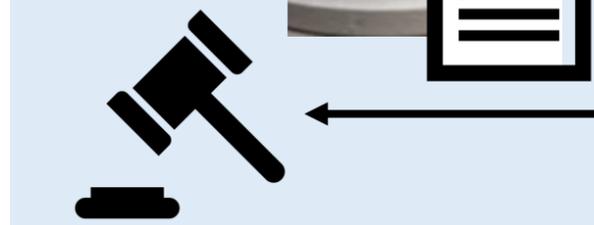


Expert Witness

Source of Bias (F)

**TOTAL ERROR = A+F+G  
= Presentation Error**

# Traditional Process



Source of Bias (G)

# Model Acquisition

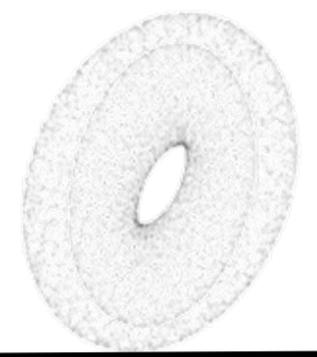


Source of Error (A)



Source of Bias (F)

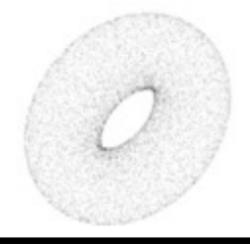
Raw data output



Clean Raw data

Source of Error (B)

Cleaned output

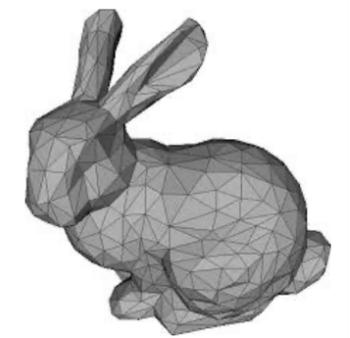


Point to surface meshing

Source of Error (C)

# Three-Dimensional Process

Mesh Solid



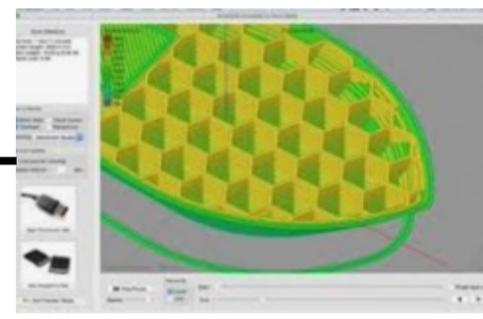
Print scanned data into solid



Source of Error (E)

GCODE

Slice mesh solid into GCODE instructions for printing



Source of Error (D)

**Traditional Process**



Crime Scene

*Model Acquisition*



Source of Error (A)

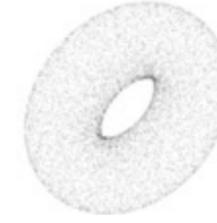
*Raw data output*



Clean Raw data

Source of Error (B)

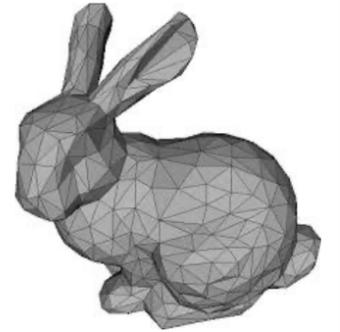
*Cleaned output*



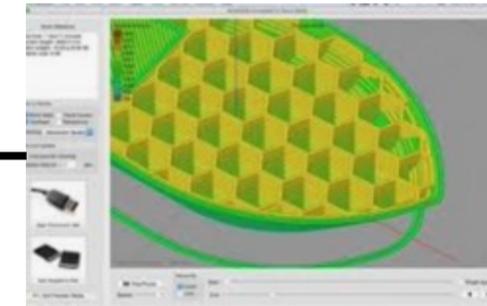
Point to surface meshing

Source of Error (C)

*Mesh Solid*



Slice mesh solid into GCODE instructions for printing



Source of Error (D)

**GCODE**

Print scanned data into solid



Source of Error (E)

*Printed Object*



*Expert Witness*



Source of Bias (F)

*Expert report and object for Jury*



*Court Room*



Source of Bias (G)

# Traditional Process



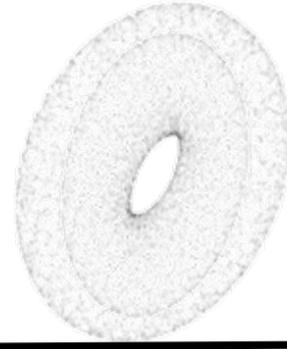
Crime Scene

Model Acquisition



Source of Error (A)

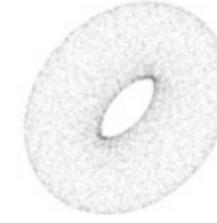
Raw data output



Clean Raw data

Source of Error (B)

Cleaned output

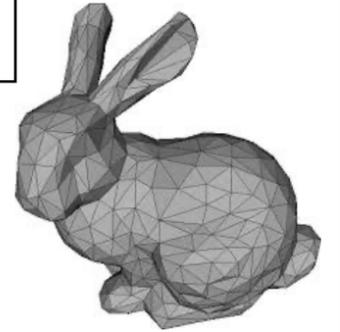


Point to surface meshing

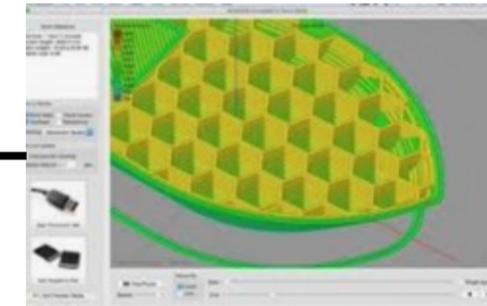
Source of Error (C)

$$\text{TOTAL ERROR} = (A+B+C+D+E) + \text{Presentation Error} = \text{Process Error} + \text{Presentation Error}$$

Mesh Solid



Slice mesh solid into GCODE instructions for printing



Source of Error (D)

GCODE

Print scanned data into solid



Source of Error (E)

Printed Object



Expert Witness



Source of Bias (F)

Expert report and object for Jury



Court Room



Source of Bias (G)

# Collection



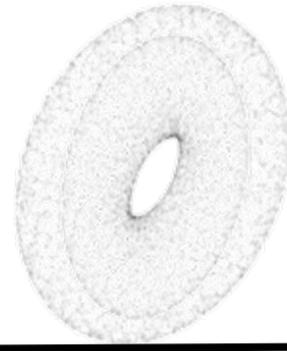
Crime Scene

Model Acquisition



Source of Error (A)

Raw data output

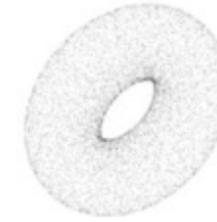


# Creation

Clean Raw data

Source of Error (B)

Cleaned output



Point to surface meshing

Source of Error (C)

# Presentation

Expert report and object for Jury



Expert Witness



Source of Bias (F)

Court Room



Source of Bias (G)

Printed Object



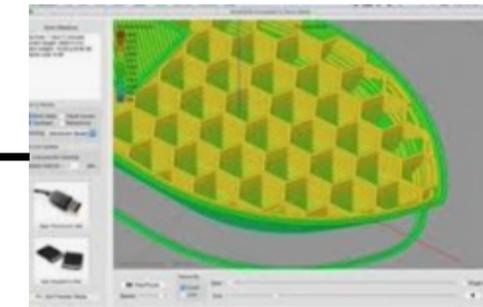
Print scanned data into solid



Source of Error (E)

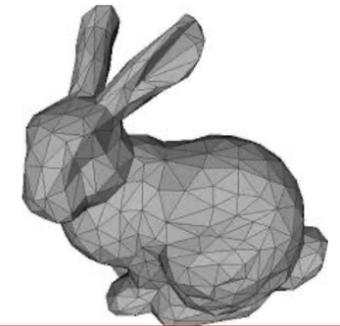
GCODE

Slice mesh solid into GCODE instructions for printing



Source of Error (D)

Mesh Solid



Manufacture

# Collection



Crime Scene

Model Acquisition



Source of Error (A)

Raw data output



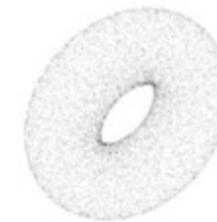
**Collection Error = A**

# Creation

Clean Raw data

Source of Error (B)

Cleaned output



Point to surface meshing

Source of Error (C)

**Creation Error = B + C**

**Presentation Error = G + F**

Expert report and object for Jury



Expert Witness



Source of Bias (F)

Court Room



Source of Bias (G)

**Manufacture Error = D + E**

Printed Object



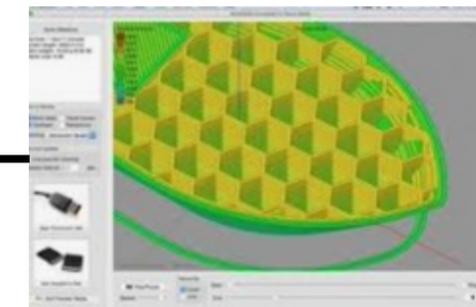
Print scanned data into solid



Source of Error (E)

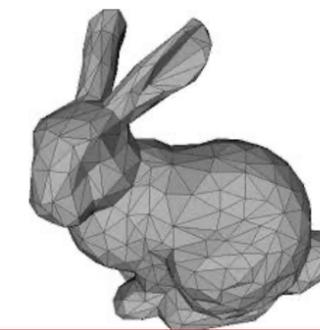
**GCODE**

Slice mesh solid into GCODE instructions for printing



Source of Error (D)

Mesh Solid



**Manufacture**

# Collection



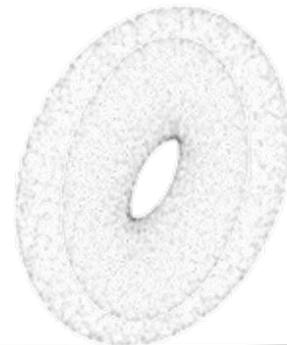
Crime Scene

Model Acquisition



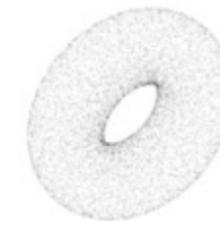
Source of Error (A)

Raw data output



# Creation

Cleaned output



Clean Raw data

Source of Error (B)

Point to surface meshing

Source of Error (C)

**TOTAL ERROR = Collection Error + Creation Error + Manufacture Error + Presentation Error**

Court Room



Source of Bias (G)

Expert report and object for Jury



Expert Witness



Source of Bias (F)

Printed Object



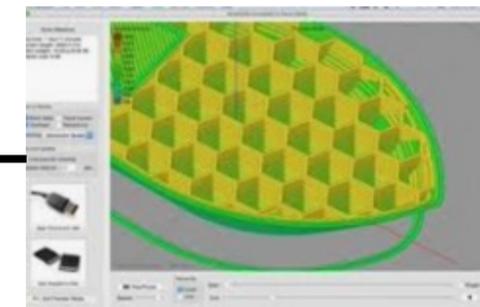
Print scanned data into solid



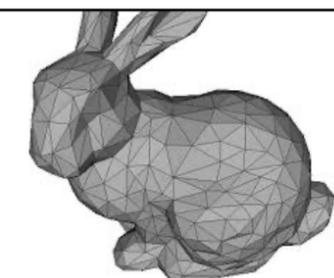
Source of Error (E)

**GCODE**

Slice mesh solid into GCODE instructions for printing



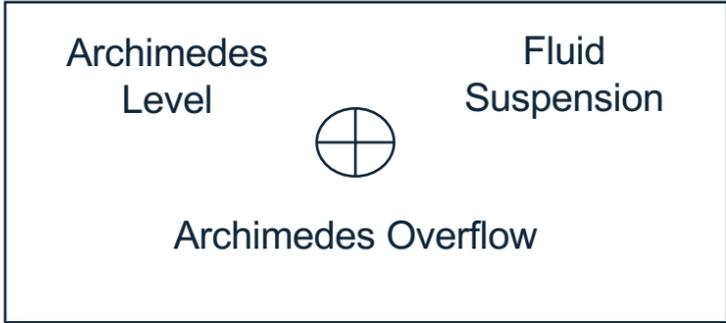
Source of Error (D)



**Manufacture**

# Generic Method

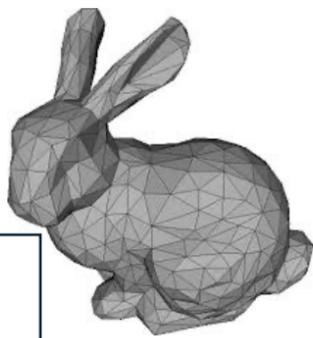
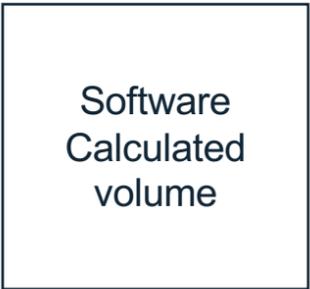
Precisely machined Volume



$V_m$



$V_s$



Mesh Solid

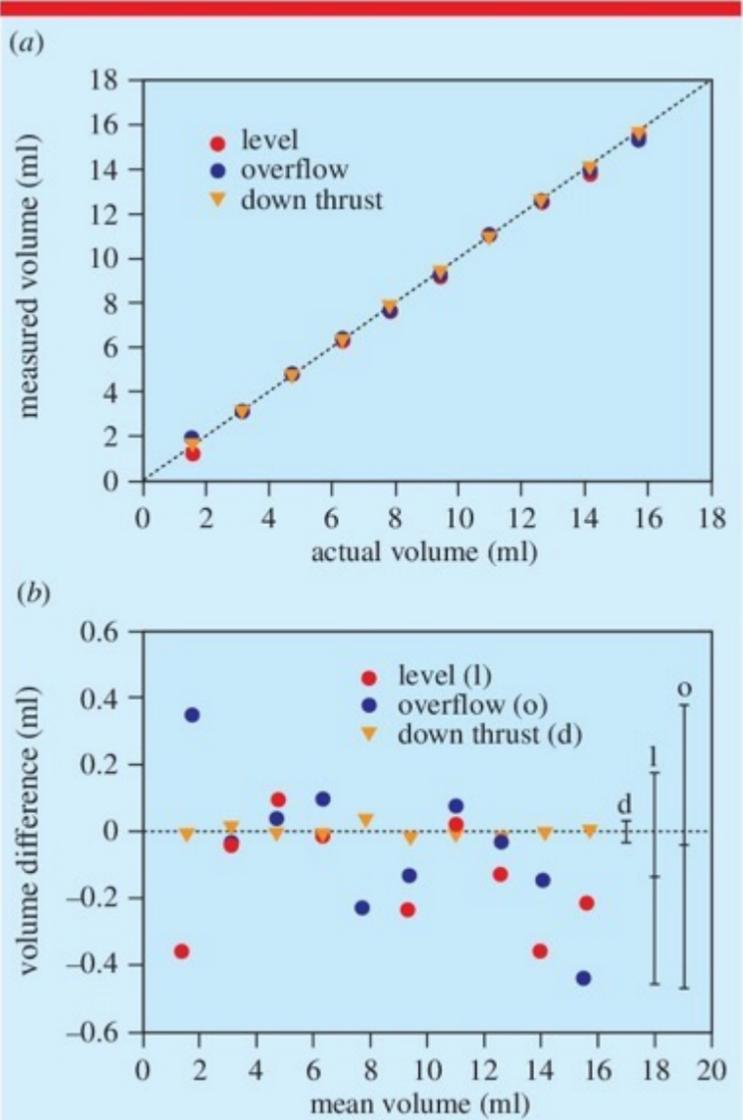
Point to surface meshing

Cleaned output

Clean Raw data

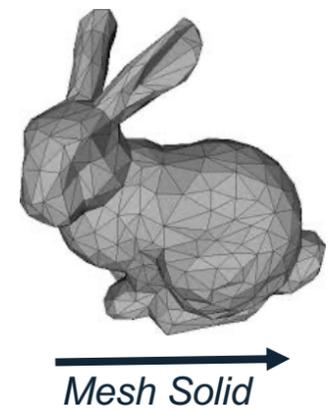
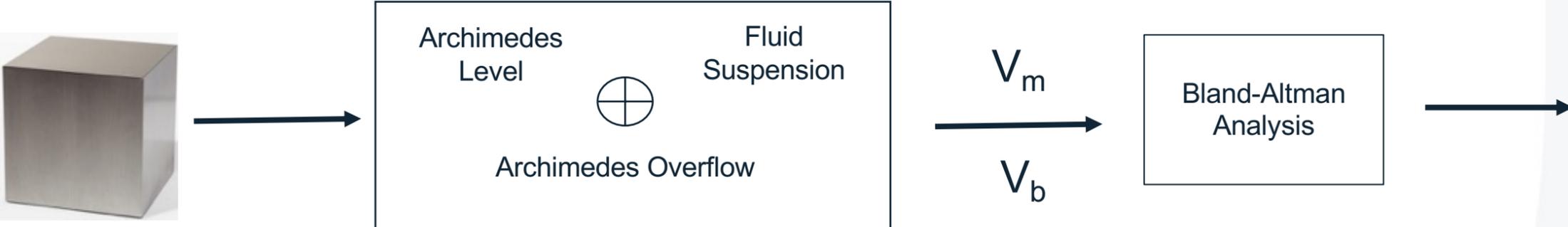
Raw data output

Model Acquisition

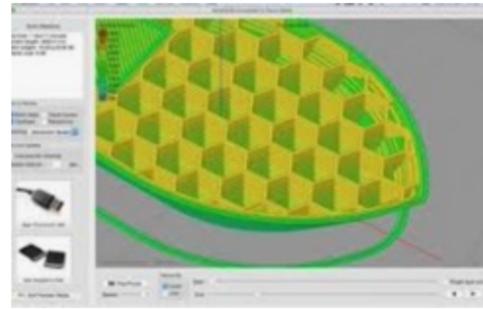


Hughes, S.W., 2005. Archimedes revisited: a faster, better, cheaper method of accurately measuring the volume of small objects. *Physics education*, 40(5), p.468.

# Extension: Build Error



Slice mesh solid into GCODE instructions for printing



**GCODE**



Print scanned data into solid



# Example

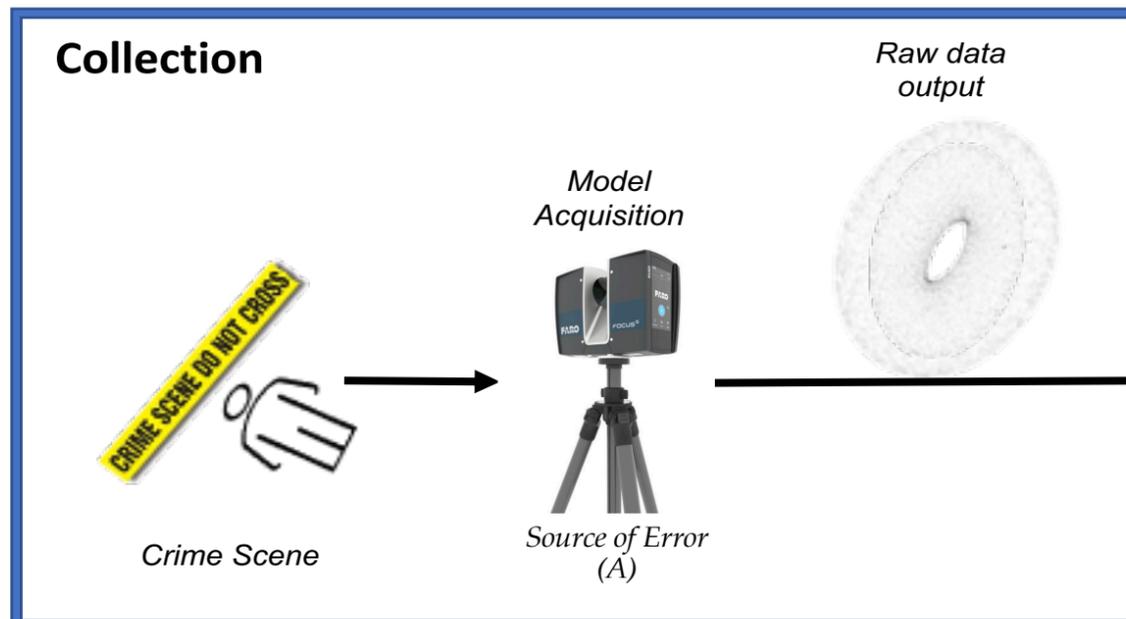


We use an iPhone 12 Pro Max and an iPad Pro to scan common items. Both have LIDAR sensors. Both are capable of 3D imaging. Both are capable of photogrammetry. We use Scandy Pro to capture a model on the phone and output a data file.

What does forensic science and Star Trek: Picard have in common?



Recall our context of low cost tool

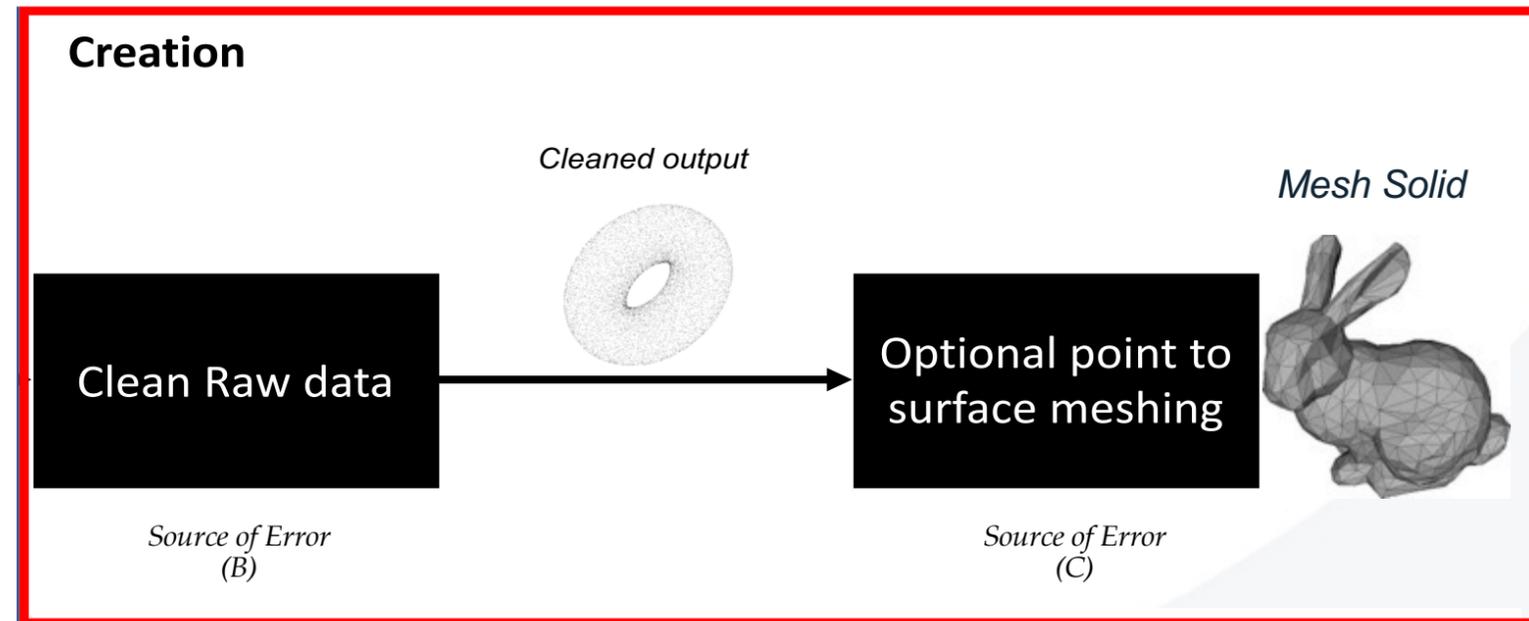
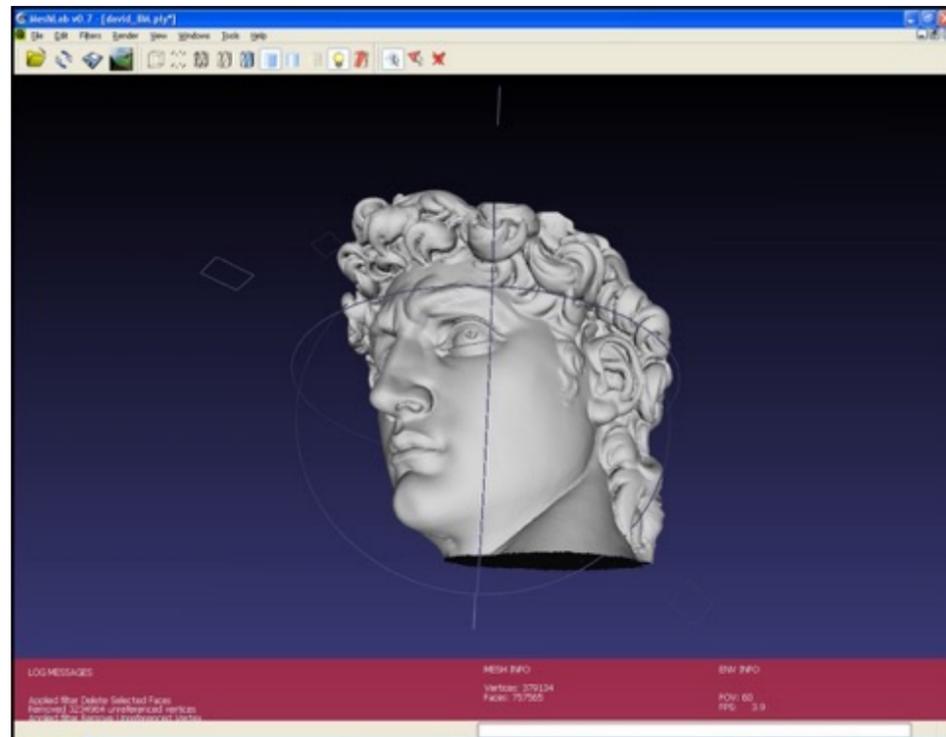
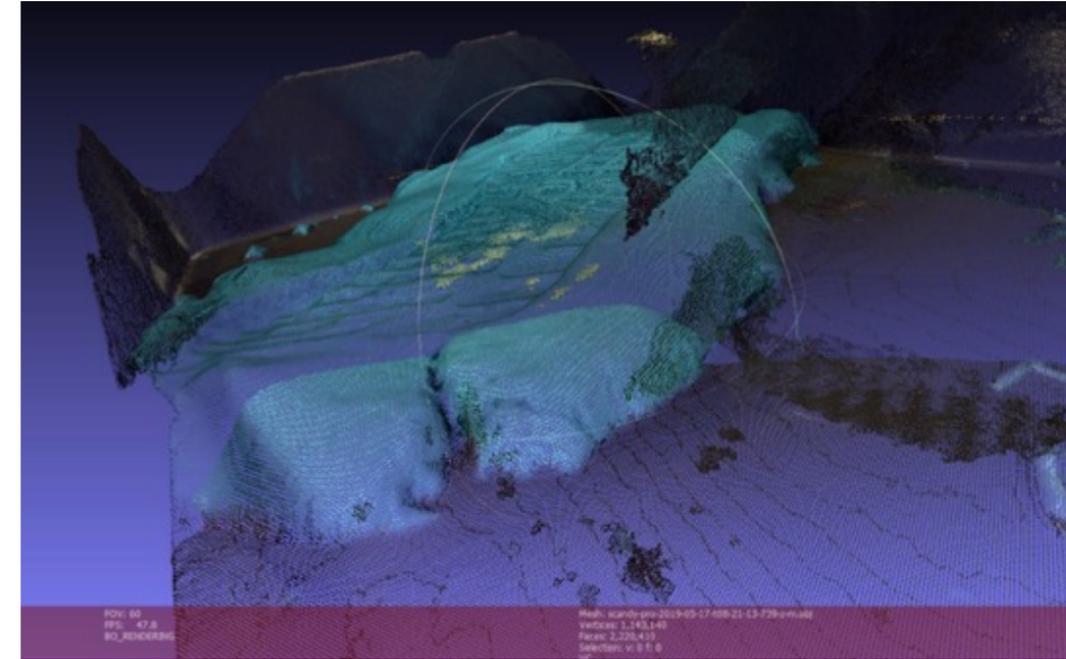


# Example

The file from Scandy Pro is exported as a mesh solid and loaded into MeshLab. Quality assurance steps are taken to ensure the model is closed watertight mesh.

The volume of the solid is then calculated in software  $V_s$ .

The final calculated volume of the mesh solid contains all the errors of this pipe.

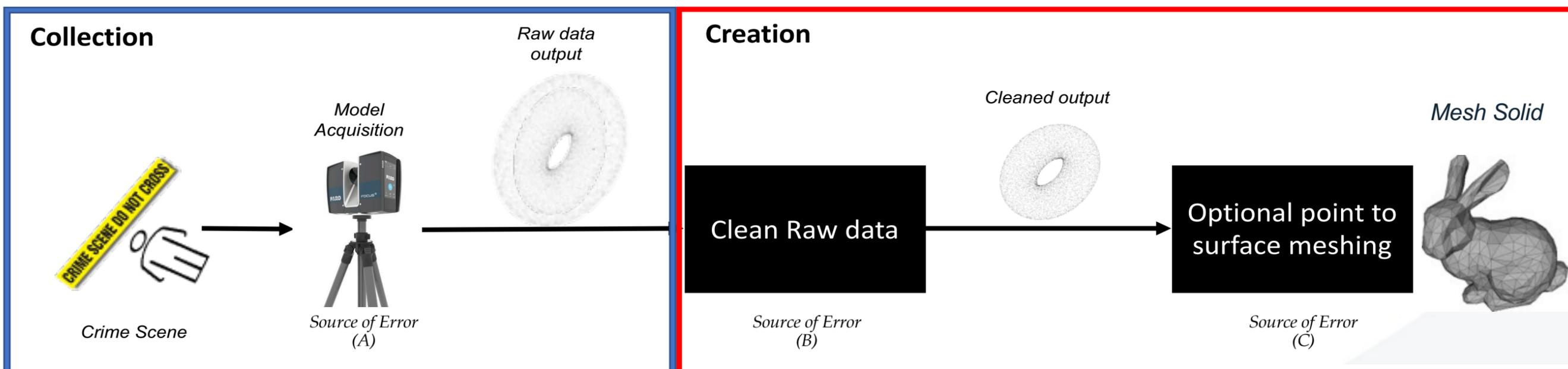
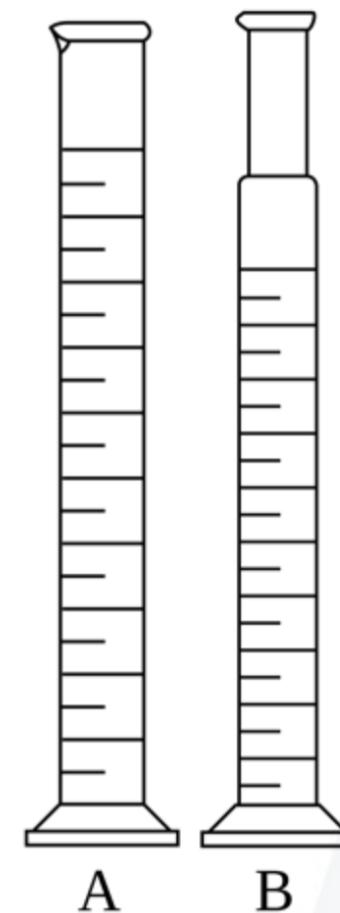




Exact volume will be calculated using the Volume displacement method. Objects will be submerged in a volume of liquid to measure displacement.

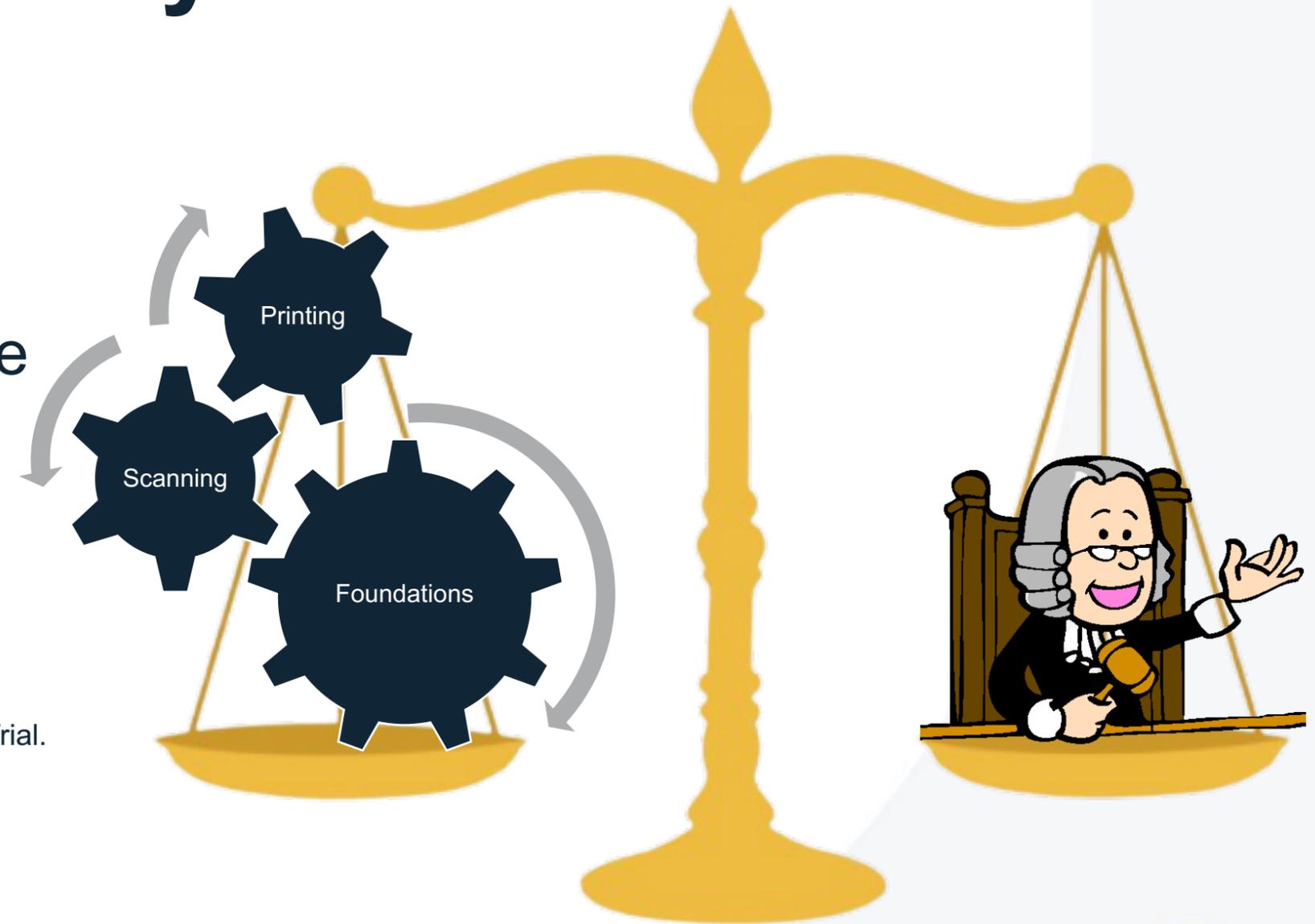
$V_m =$   
starting volume of water – finish volume of water.

This value is then compared with the scanned volume from each application capable of measuring volume/ outputting an STL solid.

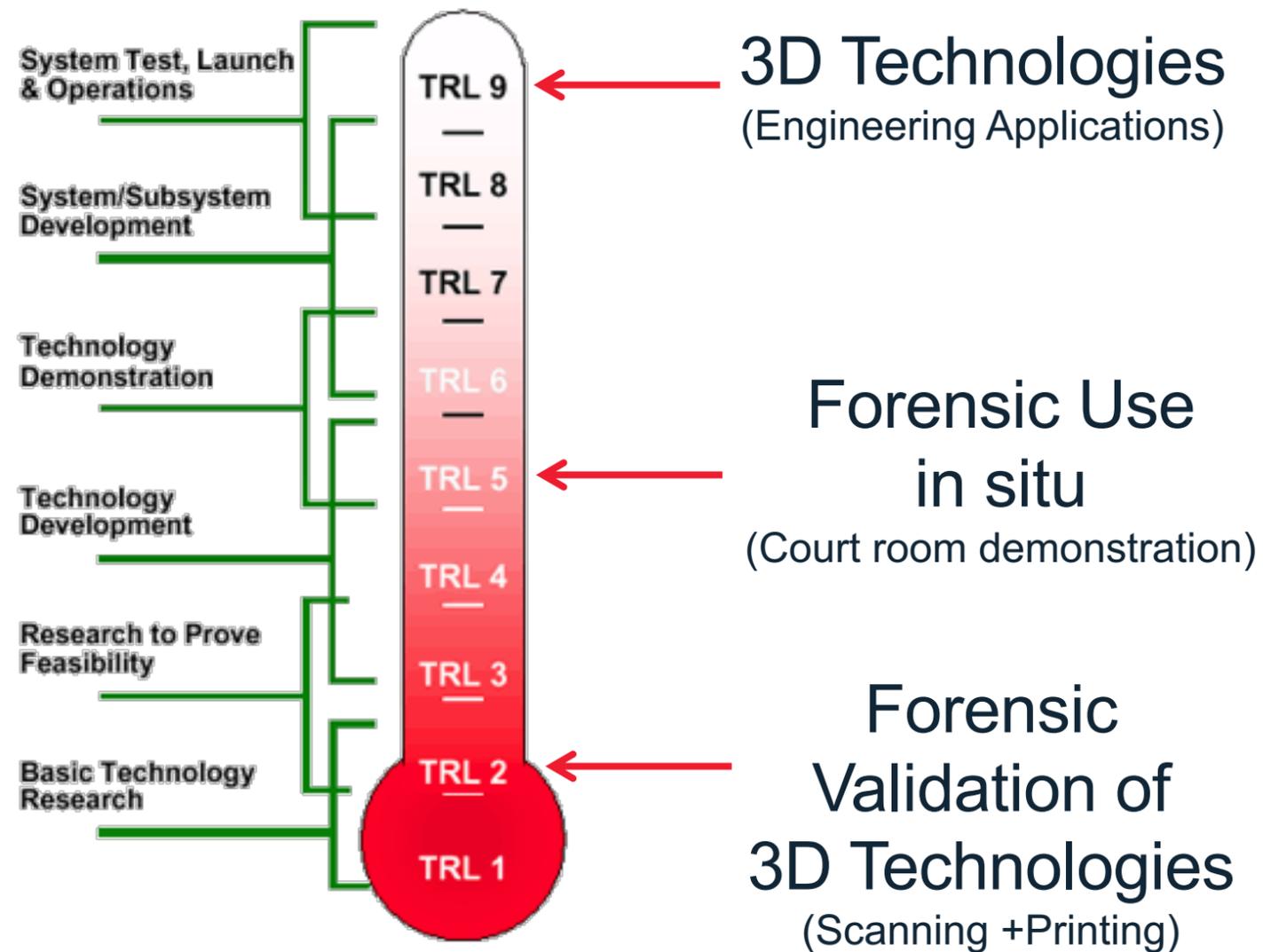


# A word on Regional Validity

- **Assumption:** Without foundational validity the pioneering results from this technology may risk continual challenge in being admitted.
- UK vs US vs AU perspectives on the Judge as the gate keeper.
  - Weinberg, M. 2020. Juries, Judges, and Junk Science – Expert Evidence on Trial. AAS/AAL Symposium.



# So where are we?



What does forensic science and Star Trek: Picard have in common?



# Acknowledgments

## Co Authors

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### Image Credits:

Star Trek (1967), Roddenberry, G. Desilu Productions.

Star Trek Voyager (1997), Berman, R. Paramount Network Television.

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